Spatial shape of avalanches

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(Received 8 August 2017; published 14 December 2017)

In disordered elastic systems, driven by displacing a parabolic confining potential adiabatically slowly, all advance of the system is in bursts, termed avalanches. Avalanches have a finite extension in time, which is much smaller than the waiting time between them. Avalanches also have a finite extension \( \ell \) in space, i.e., only a part of the interface of size \( \ell \) moves during an avalanche. Here we study their spatial shape \( \langle S(x) \rangle \), given \( \ell \), as well as its fluctuations encoded in the second cumulant \( \langle S^2(x) \rangle \). We establish scaling relations governing the behavior close to the boundary. We then give analytic results for the Brownian force model, in which the microscopic disorder for each degree of freedom is a random walk. Finally, we confirm these results with numerical simulations. To do this properly we elucidate the influence of discretization effects, which also confirms the assumptions entering into the scaling ansatz. This allows us to reach the scaling limit already for avalanches of moderate size. We find excellent agreement for the universal shape and its fluctuations, including all amplitudes.

DOI: 10.1103/PhysRevE.96.062116

I. INTRODUCTION

Many physical systems in the presence of disorder, when driven adiabatically slowly, advance in abrupt bursts, called avalanches. The latter can be found in the domain-wall motion in soft magnets [1], in fluid contact lines on a rough surface [2], in slip instabilities leading to earthquakes on geological faults, or in fracture experiments [3]. In magnetic systems they are known as Barkhausen noise [4–6]. In some experiments [2], but better in numerical simulations [7–9], it can be seen that avalanches have a well-defined extension, both in space and in time. In theoretical models, this is achieved without the introduction of a short-scale cutoff. This is nontrivial: The velocity in an avalanche, i.e., its temporal shape, could well decay exponentially in time, as is the case in magnetic systems in the presence of eddy currents [10,11]. However, it can be shown that generically an avalanche stops abruptly. In a field-theoretic expansion [12] the velocity of the center of mass inside an avalanche of duration \( T \) was shown to be well approximated by

\[
(\dot{u}(t = xT))_T \simeq |T(x(1 - x))|^{-\gamma} \exp\left( A \left[ \frac{1}{2} - x \right] \right),
\]

where \( 0 < x < 1 \). The exponent \( \gamma = (d + \xi)/\zeta \) is given by the two independent exponents at depinning, the roughness \( \xi \) and the dynamical exponent \( \zeta \). The asymmetry \( A \) is negative for \( d \) close to \( d_c \), i.e., \( A \approx -0.336(1 - d/d_c) \), skewing the avalanche towards its end, as observed in numerical simulations in \( d = 2 \) and \( 3 \) [13]. In one dimension, the asymmetry is positive [14]. While more precise theoretical expressions are available [12], an experimental or numerical verification of these finer details is difficult and currently lacking.

In this article we analyze not the temporal but the spatial shape \( \langle S(x) \rangle \) of an avalanche of extension \( \ell \). To define this shape properly it is, as for the temporal shape, important that an avalanche has well-defined end points in space and a well-defined extension \( \ell \).

Let us start to review where the theory on avalanches stands. The systems mentioned above can efficiently be modeled by an elastic interface driven through a disordered medium (see [15,16] for a review of basic properties). The energy functional for such a system has the form

\[
\mathcal{H}[u] = \int_1^x \frac{1}{2} |\nabla u(x)|^2 + \frac{m^2}{2} |u(x) - w|^2 + V(x, u(x)).
\]

The term \( V(x, u) \) is the disorder potential, correlated as \( V(x, u) V(x', u') = 1/\Delta \delta(x - x')R(u - u') \). The term proportional to \( m^2 \) represents a confining potential centered at \( w \). Changing \( w \) allows us to study avalanches, either in the statics by finding the minimum-energy configuration or in the dynamics, at depinning, by studying the associated Langevin equation (usually at zero temperature)

\[
\gamma \partial_t u(x, t) = -\frac{\delta \mathcal{H}[u]}{\delta u(x)} \big|_{u(x) = u(x, t)} = \nabla^2 u(x, t) - m^2 [u(x, t) - w] + V(x, u(x, t)).
\]

The random force \( F(x, u) \) in Eq. (3) is related to the random potential \( V(x, u) \) by \( F(x, u) = -\delta_b V(x, u) \). It has correlations \( \langle F(x, u) F(x', u') \rangle = 1/\Delta \delta(x - x')\Delta(u - u') \), related to the correlations of the disorder potential via \( \Delta(u) = -R(u) \). To simplify notation, we rescale time by \( t \rightarrow t/\gamma \), which sets the coefficient \( \gamma = 1 \) in Eq. (3).

It is important to note that \( \partial_t u(x, t) \geq 0 \), thus the movement is always forward (Middleton’s theorem [17]). This property is important for the avalanche dynamics and for a proper construction of the field theory. Much progress was achieved in this direction over the past years, due to a powerful method, the functional renormalization group. It was first applied to a precise estimation of the critical exponents [18–23]. Later it was realized and verified in numerical simulations that the central object of the field theory is directly related to the correlator of the center-of-mass fluctuations, both in the statics [24] and at depinning [25].

To build the field theory of avalanches, one first identifies the upper critical dimension, \( d_c = 4 \) for standard (short-range) elasticity as in Eq. (2) or \( d_c = 2 \) for long-range elasticity. For depinning, it was proven that at this upper critical dimension, the relevant (i.e., mean-field) model is the Brownian force model (BFM): an elastic manifold with the Langevin equation (3), in which the random force experienced by each
degree of freedom has the statistics of a random walk \([26,27]\), i.e.,
\[
\Delta(0) - \Delta(u - u') = \sigma |u - u'|, \tag{4}
\]
The BFM then serves as the starting point of a controlled \(\varepsilon\) expansion with \(\varepsilon = d_c - d\) around the upper critical dimension. This is relevant both for equilibrium, i.e., the statics \([7,28–31]\), and at depinning \([10,32]\). Results are now available for the avalanche-size distribution, the distribution of durations, and the temporal shape, both at fixed duration \(T\) as given in Eq. (1) and at fixed size \(S\).

Much less is known about the spatial shape, i.e., the expectation of the total advance inside an avalanche as a function of space, given a total extension \(\ell\). To simplify our consideration and notation, we consider dimension \(d = 1\), in which there is a function \(\langle S(x) \rangle_{\ell, r}\), vanishing for \(|x| > \frac{\ell}{2}\).

Most results currently available were obtained for the BFM. An important step was achieved in Ref. \([33]\). Starting from an exact functional for the probability to find an avalanche of shape \(S(\ell)\) (reviewed in Sec. II), a saddle-point analysis permitted Thierry \textit{et al.} to obtain the shape for avalanches of size \(S\), with a large aspect ratio \(S/\ell^d \gg 1\). It was shown that in this case the mean avalanche shape grows as \(\langle S(x) \rangle_{\ell,s} \sim (x - \ell/2)^{\eta}\) close to the (left) boundary. A subsequent expansion in \(\frac{\ell}{S}\) allowed the authors to include corrections for smaller sizes. This did not change the scaling close to the boundary.

We believe that this scaling does not pertain to generic avalanches.\(^1\) Avalanches which have an extension \(\ell \ll L_u = m^{-1}\), i.e., the infrared cutoff set by the confining potential in Eq. (2) or (3), should obey the scaling form
\[
\langle S(x) \rangle_{\ell} = \ell^\xi g(x/\ell), \tag{5}
\]
where \(g(x)\) is nonvanishing in the interval \([-1/2,1/2]\). Integrating this relation over space yields \(S \sim \ell^{d+\xi}\), the canonical scaling relation between size and extension of avalanches, confirming the ansatz (5).

We now want to deduce how \(g(x)\) behaves close to the boundary. For simplicity of notation, we write our argument for the left boundary in \(d = 1\). Imagine the avalanche dynamics for a discretized representation of the system. The avalanche starts at some point, which in turn triggers movement of its neighbors, and so on. This will lead to a shock front propagating outward from the seed to the left and to the right. As long as the elasticity is local as in Eq. (2), the dynamics of these two shock fronts is local: Consider the joint probability for the advance of all points conditioned on the position of the \(i\)th point away from the boundary, with \(i\) being much smaller than the total extension \(\ell\) of the avalanche (in fact, we only need that the avalanche started right of this point), then we expect that the joint probability distribution for the advance of points \(i\) to \(i - 1\) depends on \(i\), but is independent of the size \(\ell\). Thus we expect that in this discretized model the shape \(\langle S(x - r_1) \rangle\) close to the left boundary \(r_1\) is independent of \(\ell\). Let us call this the boundary-shape conjecture. We will verify later in numerical simulations that it indeed holds.

Let us now turn to avalanches of large size \(\ell\) so that we are in the continuum limit studied in the field theory. Our conjecture then implies that the shape \(\langle S(x - r_1) \rangle\) measured from the left boundary \(r_1 = -\ell/2\) is independent of \(\ell\). In order to cancel the \(\ell\) dependence in Eq. (5) this in turn implies that
\[
g(x - 1/2) = B \times (x - 1/2)^{\xi}, \tag{6}
\]
with some amplitude \(B\). For the Brownian force model in \(d = 1\), the roughness exponent is
\[
\xi_{\text{BFM}} = 4 - d = 3. \tag{7}
\]
We will show below that in the BFM the amplitude \(B\) is given by
\[
B = \frac{\sigma}{2\Delta}. \tag{8}
\]
We further show that the function \(g(x) = \langle S(x) \rangle_{\ell=1}\) for the BFM can be expressed in terms of a Weierstrass-\(\wp\) function and its primitive function, the Weierstrass-\(\xi\) function [see Eqs. (84), (28), and (62)]. This function is plotted in Fig. 1 (black solid curve). For comparison, we also give the shape for avalanches with a large aspect ratio \(S/\ell^d\) \([33]\), rescaled to the same peak amplitude (green dashed curve). The two shapes are significantly different.

We would like to mention the study \([34]\) of avalanche shapes, conditioned to start at a given seed and having total size \(S\). This particular conditioning renders the solution in the BFM essentially trivial: The spatial dependence becomes that of diffusion, so the final result is the center-of-mass velocity folded with the diffusion propagator. The advantage of this approach is that one can relatively simply include perturbative corrections in \(4 - d\) away from the upper critical dimension. A shortcoming is that the such defined averaged shape is far from sample avalanches seen in a simulation: In particular, one of the key features, namely, the finite extension of each avalanche encountered in a simulation, is lost. When applied to experiments, it is furthermore questionable whether one will be able to identify the seed of an avalanche. For these reasons,

\(^1\)This is contrary to the claim made in Ref. \([33]\) that in the BFM, also for generic avalanches, the scaling close to the boundary is 4. We show in Appendix C, by reanalyzing the data of \([33]\), that they favor an exponent 3 instead of 4, in agreement with our results (6) and (7).
we will develop below the theory of avalanches with a given spatial extension \( \ell \).

II. PROBABILITY OF A GIVEN SPATIAL AVALANCHE SHAPE

Here we review some basic results of Ref. [33] for the Brownian force model. Suppose that the interface is at rest in the configuration \( u_1(x) = u(x,t_1) \) and then an avalanche occurs which transforms it to configuration \( u_2(x) = u(x,t_2) \). We define \( S(x) := u_2(x) - u_1(x) \) as the total advance at point \( x \), which we call the spatial shape of the avalanche.

We start with a simplified derivation of the key formula of Ref. [33], given below in Eq. (15). To this aim, we write the MSR action for the dynamics of the interface, obtained from a time derivative of Eq. (3), as [26,27,35]

\[
e^{-S[\bar{u},u]} = \exp \left( \int_{x,t} \bar{u}(x,t) \left[ -\partial_t \bar{u}(x,t) + \nabla^2 \bar{u}(x,t) - m^2 \bar{u}(x,t) + \bar{u} F(x,u,u(x,t)) + \bar{u} f(x,t) \right] \right). \tag{9}
\]

There are no avalanches without driving and the last term has been added for this purpose. We want to drive the system with a force kick at \( t = 0 \), i.e.,

\[
f(x,t) = \delta(t) w(x). \tag{10}
\]

Note that, compared to the notation in Refs. [26,27,35], we have absorbed a factor of \( m \) into \( w \). Here, as in Ref. [36], it is a kick in the force and there it is a kick in the displacement. Indeed, if we change the well position \( w \) instantaneously from \( w \) to \( w + \delta w \) at time \( t = 0 \), i.e., \( w(t) = w + \delta w \theta(t) \), then

\[
f(x,t) = \delta(t) m^2 \delta w. \tag{11}
\]

Our choice (10) is made so that the limit of \( m \rightarrow 0 \) can be taken.

To obtain static quantities (as the avalanche-size distribution), one can use a time-independent response field \( \bar{u}(x,t) = \bar{u}(x) \) [26,27]. Integrating over times from \( t_1 \) before the avalanche to \( t_2 \) after the avalanche and using that the interface is at rest at these two moments yields\(^2\)

\[
e^{-S[\bar{u},\bar{S}]} = \exp \left( \int_x \bar{u}(x) \left[ w(x) + \nabla^2 S(x) - m^2 S(x) \right. \right. \\
+ F(x,u_2(x)) - F(x,u_1(x)) \left. \right] \right). \tag{12}
\]

Averaging over disorder, using \( \bar{F}(x,u) F(x',u') = \delta^d(x - x') \Delta(u - u') \), we obtain

\[
e^{-S[\bar{u},\bar{S}]} = \exp \left( \int_x \bar{u}(x) \left[ w(x) + \nabla^2 S(x) - m^2 S(x) \right. \right. \\
+ \bar{u}(x)^2 \left[ \Delta(0) - \Delta(S(x)) \right] \left. \right) \right). \tag{13}
\]

Integrating over \( \bar{u}(x) \) yields

\[
\int \mathcal{D}[\bar{u}] e^{-S[\bar{u},u]} \approx \prod_x \frac{1}{\sqrt{\Delta(0) - \Delta(S(x))}} \times \exp \left( - \int_x \frac{m^4 S(x)}{4 \sigma} + \frac{[\nabla^2 S(x)]^2}{4 \sigma S(x)} \right). \tag{14}
\]

This formula is a priori exact for any disorder correlator \( \Delta(u) \). For the BFM \( \Delta(0) - \Delta(\sigma) \equiv \sigma \). Thus we obtain, upon simplification in the limit of \( u(x) \rightarrow 0 \) [33],

\[
\text{Prob}[S(x)] \simeq \prod_x \frac{1}{\sqrt{S(x)}} \exp \left( - \int_x \frac{m^4 S(x)}{4 \sigma} + \frac{[\nabla^2 S(x)]^2}{4 \sigma S(x)} \right). \tag{15}
\]

Changing variables to \( \phi(x) := \sqrt{S(x)} \) eliminates the factor of \( \prod_x S(x)^{-1/2} \). A saddle point for avalanches with a large aspect ratio \( S/\ell^4 \), where \( S \) is the avalanche size and \( \ell \) its spatial extension, can be obtained by varying with respect to \( \phi(x) \). The solution of this saddle-point equation is plotted in Fig. 1 (green dashed line), in contrast to the shape for generic avalanches (black solid line) to be derived later. See also Fig. 12 for a numerical validation of the saddle-point solution in Ref. [33].

III. EXPECTATION OF \( S(x) \) IN AN AVALANCHE EXTENDING FROM \(-\ell/2\) TO \( \ell/2\)

A. Generalities

We consider avalanches in the BFM in \( d = 1 \) dimensions. To this aim, we start from Eq. (13), using the correlator (4). This yields

\[
e^{-S_{\text{static}}[\bar{u},S]} = \exp \left( \int_x \bar{u}(x) \left[ w(x) + \nabla^2 S(x) - m^2 S(x) \right. \right. \\
+ \sigma \bar{u}(x)^2 S(x) \left. \right) \right). \tag{16}
\]

We now wish to evaluate the generating function for avalanche sizes

\[
\bar{P}[\bar{\lambda}(x)] := \exp \left( \int_x \bar{\lambda}(x) S(x) \right) = \int \mathcal{D}[S] \mathcal{D}[\bar{u}] \exp \left( \int_x \bar{\lambda}(x) S(x) - S_{\text{FBM}}[\bar{u},S] \right). \tag{17}
\]

A crucial remark is that \( S(x) \) appears linearly in the exponential; thus integrating over \( S(x) \) enforces that \( \bar{u}(x) \) obeys the differential equation [36]

\[
\ddot{u}(x) - m^2 \bar{u}(x) + \sigma \bar{u}(x)^2 = -\lambda(x). \tag{18}
\]

This is an instanton equation. Suppose we have found its solution, which for simplicity we also denote by \( \bar{u}(x) \). Then

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\(^2\)This does not take into account the change of measure from \( \prod_x d\bar{u}(x,t) \) to \( dS(x) \), and similarly for \( \bar{u}(x,t) \). Our simplified derivation thus misses an additional global factor in Eq. (50) of [33]. In particular, the result (15) is incorrect for a single degree of freedom. On the other hand, integrating Eq. (13) over \( S(x) \) still gives the correct instanton equation (17), which can be derived independently from this argument (see, e.g., [36]).
Eq. (17) simplifies considerably to [36]
\[ \mathcal{P}[\lambda(x)] := \exp \left( \int_x \lambda(x) S(x) \right) = \exp \left( \int_x w(x) \tilde{u}(x) \right). \]  
(19)
In Ref. [36], a solution for \( \lambda(x) \) in the form
\[ \lambda(x) = -\lambda_1 \delta(x - r_1) - \lambda_2 \delta(x - r_2) \]  
(20)
was given in the limit of \( \lambda_{1,2} \rightarrow \infty \). This solution ensures that if the interface has moved at positions \( r_1 \) or \( r_2 \), the expression \( \exp[\int_x \lambda(x) S(x)] \) is 0; otherwise it is 1. The probability that the interface has not moved at these two positions \( r_1 \) and \( r_2 \) thus is
\[ \mathcal{P}_{r_1,r_2} = \exp \left( \int_x w(x) \tilde{u}(x) \right). \]  
(21)
We now consider driving at \( x \) between the two points \( r_1 \) and \( r_2 \). In order that the probability (21) decreases for an increase in the driving at \( x \), we need that
\[ \tilde{u}(x) < 0, \quad r_1 < x < r_2. \]  
(22)
This helps us to select the correct solution (see Appendix A). Call \( \tilde{u}_0(x) \) this solution. According to [36], it reads
\[ \tilde{u}_0(x) = \frac{1}{(r_2 - r_1)^2} f \left( \frac{2x - r_1 - r_2}{2(r_2 - r_1)} \right). \]  
(23)
Its extension is
\[ \ell = r_2 - r_1. \]  
(24)
It further depends on the dimensionless combination \( \frac{L}{L_m} = \ell m \).

In the massless limit, i.e., for
\[ \frac{\ell}{L_m} = \ell m \ll 1, \]  
(25)
Eq. (18) is simplified and the function \( f(x) \) satisfies
\[ f''(x) + f(x)^2 = 0. \]  
(26)
Solutions of Eq. (18) for finite \( m \) exist and the analysis could be repeated for this case.

This solution diverges with a quadratic divergence at \( x = \pm 1/2 \). We review in Appendix A its construction. We see there that it is a negative-energy solution with energy \( -\mathcal{E}_1 \), where
\[ \mathcal{E}_1 = \frac{8\pi^3 \Gamma(\frac{1}{2})^6}{3 \Gamma(\frac{3}{2})^6}. \]  
(27)
It reads
\[ f(x) = -6\mathcal{P} \left( x + 1/2; g_2 = 0, g_3 = \frac{\Gamma(\frac{1}{2})^{18}}{(2\pi)^6} \right). \]  
(28)
The function \( \mathcal{P} \) is the Weierstrass \( \mathcal{P} \) function. The parameter \( g_3 \) satisfies
\[ g_3 \equiv \frac{\mathcal{E}_1}{18}. \]  
(29)
and the solution respects the constraint (22). For later simplifications we note the relations
\[ \frac{2}{5} f^3(x) + f'(x)^2 = -36g_3 \equiv -2\mathcal{E}_1, \]  
(30)
\[ \frac{2}{5} f(x) f''(x) - f'(x)^2 = 36g_3 = 2\mathcal{E}_1. \]  
(31)

B. Driving

Let us now specify the driving function \( w(x) \) introduced in Eq. (10). There are two main choices. (i) The first is uniformly distributed random seeds (random localized driving)
\[ w(x) = w \delta(x - x_i). \]  
(32)
Here we first calculate the observable at hand and finally average, i.e., integrate, over the seed position \( x_i \). In a numerical experiment, one can take a random permutation of the \( N \) degrees of freedom and then apply a kick to each of them in the chosen order. (ii) The second is uniform driving
\[ w(x) = w. \]  
(33)
As we wish to work at first nonvanishing order in \( w \), this makes \textit{almost} no difference. Indeed, in Eq. (19) we formally have, for both driving protocols to leading order in \( w \),
\[ \exp \left( \int_x \lambda(x) S(x) \right) - 1 \]
\[ \exp \left( \int_x w \tilde{u}(x) \right) - 1 \rightarrow w \int_x \tilde{u}(x). \]  
(34)
There is, however, one caveat: If \( \tilde{u}(x) \rightarrow -\infty \), as is the case for the solution (23) at \( x = r_1,2 \), then, for localized driving, points \( x \) around these singularities are suppressed and the corresponding points have to be taken out of the integral. On the other hand, for uniform driving, the middle integral in Eq. (34) simply vanishes. In that case one has to regularize the solution, i.e., work at finite \( \lambda_{1,2} \), then take \( w \rightarrow 0 \), and only at the end take the limit \( \lambda_{1,2} \rightarrow \infty \). According to Appendix A, working at finite \( \lambda_{1,2} \) is equivalent to cutting out a piece of size \( x_0 \) around the singularity, with \( x_0 \) given by Eq. (A3). Thus, effectively, driving is restricted to the interval \( [r_1 + x_0, r_2 - x_0] \), slightly smaller than the the full interval \( [r_1, r_2] \).

For conceptual clarity and simplicity of presentation, we will work with uniformly distributed random seeds (random localized driving) below. The idea to keep in mind is that in the limit \( w \rightarrow 0 \), the driving only triggers the avalanche, but after the avalanche starts, its subsequent dynamics is independent of the driving. As a result, the avalanche shape is independent of the driving and we can choose the most convenient driving.

C. Strategy of the calculation

We now want to construct perturbatively a solution of Eq. (18) at \( m = 0 \) and \( \sigma = 1 \), i.e.,
\[ \tilde{u}''(x) + \tilde{u}(x)^2 = -\lambda(x), \]  
(35)
with
\[ \lambda(x) = -\lambda_1 \delta(x - r_1) - \lambda_2 \delta(x - r_2) + \eta \delta(x - x_0), \]  
(36)
\[ \lambda_1, \lambda_2 \rightarrow \infty. \]  
(37)
We are interested in the limit of vanishing $\eta$, i.e., at first and second order in $\eta$. This instanton solution will have the form

$$\tilde{u}(x) = \tilde{u}_0(x) + \eta \tilde{u}_1(x) + \eta^2 \tilde{u}_2(x) + \cdots.$$  \hfill (38)

It will be continuous but nonanalytic at $x = x_c$ (see Fig. 2).

Let us reconsider Eq. (19), i.e., $\exp(\int_x \lambda(x)S(x)) = \exp(\int_x u(x)\tilde{u}(x))$. Its left-hand side can be written as

$$\exp(\int_x \lambda(x)S(x)) = \int_{x_l}^{x_u} \int_{x_l}^{r_1} \int_{x_l}^{r_2} \int_0^\infty dS(x_c) \times e^{\eta S(x_c)} P(S(x_c), r_{\text{left}}, r_{\text{right}}),$$  \hfill (39)

where $P(S(x_c), r_{\text{left}}, r_{\text{right}})$ is the joint probability that the avalanche has advanced by $S(x_c)$ at $x_c$ and that it extends from $r_{\text{left}}$ to $r_{\text{right}}$, with $r_1 < r_{\text{left}} < x_c < r_{\text{right}} < r_2$.

Taking derivatives with respect to points $r_1$ and $r_2$ yields

$$\frac{\partial^2}{\partial r_1 \partial r_2} \exp(\int_x \lambda(x)S(x))$$

$$= \int_0^\infty dS(x_c) e^{\eta S(x_c)} \frac{\partial}{\partial r} P(S(x_c), r_{\text{left}}, r_{\text{right}})$$

$$= P_t(r_2 - r_1) e^{\eta S(x_c)} \left[ 1 + \eta \langle S(x_c) \rangle_{r_1} + \frac{\eta^2}{2} \langle S(x_c)^2 \rangle_{r_1} + \cdots \right].$$  \hfill (40)

Here $P_t(\ell)$ is the probability to have an avalanche with extension $\ell$ and angular brackets $\langle \cdots \rangle_{r_1}$ denote conditional averages given that the end points of the avalanches are at $r_1$ and $r_2$.

We now consider derivatives with respect to points $r_1$ and $r_2$ of the right-hand side of Eq. (19). Using the expansion (38) yields

$$\frac{\partial^2}{\partial r_1 \partial r_2} \exp(\int_x w(x)\tilde{u}(x))$$

$$= - \exp(\int_x d\tilde{u_0}(x) \left[ \int d\tilde{u_0}(x) \frac{\partial^2 \tilde{u_0}(x)}{\partial r_1 \partial r_2} \right.$$\n
$$\left. + \eta \int d\tilde{u_0}(x) \frac{\partial \tilde{u_1}(x)}{\partial r_1} + \eta^2 \int d\tilde{u_0}(x) \frac{\partial \tilde{u_2}(x)}{\partial r_1} + \cdots \right].$$  \hfill (41)

Omitted terms indicated by an ellipsis are higher order in $w$. Comparing Eqs. (40) and (41) yields, for the probability to find an avalanche with extension $\ell$,

$$P_t(\ell = r_2 - r_1) = - \exp(\int_x d\tilde{u_0}(x) \left[ \int d\tilde{u_0}(x) \frac{\partial^2 \tilde{u_0}(x)}{\partial r_1 \partial r_2} \right.$$\n
$$\left. + \eta \int d\tilde{u_0}(x) \frac{\partial \tilde{u_1}(x)}{\partial r_1} + \eta^2 \int d\tilde{u_0}(x) \frac{\partial \tilde{u_2}(x)}{\partial r_1} + \cdots \right].$$  \hfill (42)

We now have to specify the driving. Following the discussion in Sec. III B, we have to either use uniform driving restricted to $[r_1 + x_0, r_2 - x_0]$ or choose random seeds $x_0$ uniformly distributed between $r_1$ and $r_2$. Here we write formulas for the latter, choosing $w(x) = w(\delta(x - x_0))$. This yields

$$P_t(\ell = r_2 - r_1) = -w \int_{r_1}^{r_2} dx_1 e^{\eta \tilde{u}_0(x_1)} \frac{\partial^2 \tilde{u}_0(x_1)}{\partial r_1 \partial r_2} + \cdots.$$  \hfill (43)

In the limit of small $w$ this becomes

$$P_t(\ell = r_2 - r_1) = -w \int_{r_1}^{r_2} dx_1 \frac{\partial^2 \tilde{u}_0(x_1)}{\partial r_1 \partial r_2} + \cdots.$$  \hfill (44)

Dropping the index $s$ for the seed position, the final formulas for the observables of interest are

$$P_t(\ell = r_2 - r_1) = -w \int_{r_1}^{r_2} dx \frac{\partial^2 \tilde{u}_0(x)}{\partial r_1 \partial r_2},$$  \hfill (45)

$$P_t(\ell = r_2 - r_1) \langle S(x_c) \rangle_{r_1} = -w \int_{r_1}^{r_2} dx \frac{\partial^2 \tilde{u}_1(x)}{\partial r_1 \partial r_2},$$  \hfill (46)

$$P_t(\ell = r_2 - r_1) \frac{\eta}{2} \langle S(x_c)^2 \rangle_{r_1} = -w \int_{r_1}^{r_2} dx \frac{\partial^2 \tilde{u}_2(x)}{\partial r_1 \partial r_2}. $$  \hfill (47)

The shape is given by the ratio of Eqs. (46) and (45), while the variance is given by the ratio of Eqs. (47) and (45).

The following calculations are structured as follows. In the next section, we give the instanton solution (35) for the extension $\ell = 1$ or, more precisely, $r_1 = -1/2$ and $r_2 = 1/2$. In the second step, performed in Sec. IV, we reconstruct the solution for general $r_1$ and $r_2$. This allows us to vary as in Eq. (41) with respect to $r_1$ and $r_2$, thus selecting only those avalanches which touch the borders at $r_1$ and $r_2$. With the normalization (45) obtained from the probability to find an avalanche of extension $\ell$ performed in Sec. IV A, this allows us to give the normalized shape and its fluctuations in Sec. IV C.

D. How to obtain the mean shape of all avalanches inside a box of size 1 and its fluctuations

We now solve Eq. (35) at $r_1 = -1/2$ and $r_2 = 1/2$. One can write down differential equations to be solved by $\tilde{u}_1(x)$ and $\tilde{u}_2(x)$. There is, however, a more elegant way to derive the perturbed instanton solution: To achieve this, we first realize that if $\tilde{u}(x)$ is a solution of $\tilde{u}''(x) + \tilde{u}(x)^2 = 0$, then $\tilde{u}_{\lambda,c}(x) := \lambda^2 \tilde{u}(\lambda x + c)$ is also a solution. We wish to construct solutions
which diverge at $x = \pm 1/2$, i.e., have extension 1, and which produce the additional term proportional to $\eta$ in Eq. (36). This can be achieved by separate solutions for the left branch, i.e., $-1/2 < x < x_c$, and the right branch $x_c < x < 1/2$. Using the symbol $f$ to indicate extension 1 as in Eq. (28), we have

\[ f_{L}^{1}(x) := \lambda_{L}^{1} f(\lambda_{L}(x + 1/2) - 1/2), \quad (48) \]

\[ x_{L}^{1}(f) = \lambda_{L}^{-1} x(\lambda_{L}^{-2} f) + \frac{1}{2} \left( \frac{1}{\lambda_{L}} - 1 \right), \quad (49) \]

\[ f_{R}^{1}(x) := \lambda_{R}^{1} f(\lambda_{R}(x - 1/2) + 1/2), \quad (50) \]

\[ x_{R}^{1}(f) = \lambda_{R}^{-1} x(\lambda_{R}^{-2} f) - \frac{1}{2} \left( \frac{1}{\lambda_{R}} - 1 \right). \quad (51) \]

The two functions must coincide at $x_c$ and their slope must change by $\eta$ or, more precisely,

\[ f_{L}^{1}(x_c) = f_{R}^{1}(x_c), \quad (52) \]

\[ \partial_{x} f_{L}^{1}(x)|_{x = x_c} = \partial_{x} f_{R}^{1}(x)|_{x = x_c} + \eta. \quad (53) \]

The second equation is written in a way to make clear that while $\lambda_{L}$ and $\lambda_{R}$ depend on $x_c$, this dependence is not included in the derivatives of Eq. (53). We make the ansatz

\[ \lambda_{L} = 1 + a\eta + c\eta^{2}, \quad (54) \]

\[ \lambda_{R} = 1 + b\eta + d\eta^{2}. \quad (55) \]

Repeatedly using Eqs. (26), (30), and (31) to eliminate higher derivatives, we find

\[ a = \frac{(2x_c - 1)f'(x_c) + 4f(x_c)}{12\xi_{1}}, \quad (56) \]

\[ b = \frac{(2x_c + 1)f'(x_c) + 4f(x_c)}{12\xi_{1}}, \quad (57) \]

\[ c = \frac{1}{288\xi_{1}^{2}} \left( 16f(x_c)[(1 - 3x_c)f'(x_c)] + (2x_c - 1)\left( f'(x_c)[(4x_c^{2} - 1)f''(x_c) + 4(3x_c + 1)f''(x_c)] + 24\xi_{1}x_c - 96f(x_c^{2}) \right) \right), \quad (58) \]

\[ d = \frac{1}{288\xi_{1}^{2}} \left( 16f(x_c)[-(3x_c + 1)f'(x_c)] - 96f(x_c)^{2} \right) + (2x_c + 1)\left( f'(x_c)[(4x_c^{2} - 1)f''(x_c) + 4(3x_c + 1)f''(x_c)] + 24\xi_{1}x_c \right), \quad (59) \]

This gives

\[ f_{L}^{1}(x) = f(x) + \frac{a}{2}[2x(1) f'(x) + 4f(x)] + \frac{\eta^{2}}{8} \left( 8(a^{2} + 2c)f(x) + 4(2x + 1)(2a^{2} + c) f'(x) + a^{2}(2x + 1) f''(x) \right) + O(\eta^{3}), \quad (60) \]

\[ f_{R}^{1}(x) = f(x) + \frac{b}{2}[2x(1) f'(x) + 4f(x)] + \frac{\eta^{2}}{8} \left( 8(b^{2} + 2d)f(x) + 4(2x + 1)(2b^{2} + d) f'(x) + b^{2}(2x + 1) f''(x) \right) + O(\eta^{3}). \quad (61) \]

For illustration we plot in Fig. 2 the order-$\eta$ solution for $x_c = 0.15$.

We are finally interested in uniformly distributed random seeds, i.e., we need to integrate these solutions over the driving point $x$ inside the box, i.e., from $-1/2$ to $1/2$. To this purpose we define

\[ F(x) := 6\zeta \left( x + \frac{1}{2}; 0, \frac{\Gamma(\frac{1}{4})^{18}}{64\pi^{6}} \right) - F_{0}, \quad F_{0} = 6\zeta \left( \frac{1}{2}; 0, \frac{\Gamma(\frac{1}{4})^{18}}{64\pi^{6}} \right) \equiv 2\pi \sqrt{3}, \quad F'(x) = f(x), \quad (62) \]

\[ F(0) = 0, \quad F(x + 1) = F(x) + 2F_{0}. \quad (63) \]

Then, subtracting the solution at $\eta = 0$, which is not needed (but whose integral is divergent), we obtain

\[ \int_{-1/2}^{x_c} \! dx \left[ f_{L}^{1}(x) - f(x) \right] = \eta a \left[ \frac{1}{2}(2x_c + 1)f(x_c) + F_{0} + F(x_c) \right] \]

\[ + \eta^{2} \left[ \frac{1}{8} a^{2}(2x_c + 1)^{2} f'(x_c) + \frac{1}{2}(a^{2} + c)(2x_c + 1)f(x_c) + c[F(x_c) + F_{0}] \right], \]

\[ \int_{x_c}^{1/2} \! dx \left[ f_{R}^{1}(x) - f(x) \right] = \eta b \left[ \frac{1}{2}(1 - 2x_c)f(x_c) + F_{0} - F(x_c) \right] \]

\[ + \eta^{2} \left[ -\frac{1}{2}(b^{2} + d)(2x_c - 1)f(x_c) - \frac{1}{8} b^{2}(2x_c - 1)^{2} f'(x_c) + d[F_{0} - F(x_c)] \right]. \quad (64) \]

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This yields the (unnormalized) expectation, given that the interface has not moved at points ±1/2:
\[
\langle e^{\phi(x)} - 1 \rangle = w \int_{-1/2}^{1/2} dx \left[ f_{\phi(x)}^R(x) - f(x) \right] + w \int_{-1/2}^{1/2} dx \left[ f_{\phi(x)}^L(x) - f(x) \right]
\]
\[
= w \eta \left\{ \frac{1}{2} f(x_c) [2(a - b)x_c + a + b] + (a - b) F(x_c) + (a + b) F_0 \right\}
\]
\[
+ w \frac{\eta^2}{8} \left\{ 4 f(x_c) [2x_c(a^2 - b^2 - c - d) + a^2 + b^2 + c + d] + [2(a - b)x_c + a + b][2(a + b)x_c + a - b] f'(x_c)
\]
\[
+ 8(c - d) F(x_c) + 8(c + d) F_0 \right\} + \cdots
\]
\[
= w \eta \frac{2 f(x_c) [f(x_c) + 2 F_0] - [F(x_c) - 2 F_0 x_c] f'(x_c)}{6 \delta_S}
\]
\[
+ w \frac{\eta^2}{144 \delta_S} \left\{ -4 x_c F(x_c) [6 \delta_S + f'(x_c) x_c^2] + 4 F_0 [12 \delta_S x_c^2 + (6 x_c^2 - 1) f'(x_c)^2] + f(x_c)^2 [8 x_c f'(x_c) - 96 F_0]
\]
\[
+ f(x_c) f'(x_c) [3 (4 x_c^4 - 1) f'(x_c) + 16 F(x_c) - 48 F_0 x_c] + (4 x_c^2 - 1) [2 F_0 x_c - F(x_c)] f'(x_c) f''(x_c) - 32 f(x_c)^3 \right\}
\]
\[
\cdot \cdot \cdot
\]
\[
=: w \eta S^1_{box}(x_c) + w \eta^2 S^2_{box}(x_c) + \cdots. \tag{65}
\]
We have termed these expressions $S^1_{box}(x_c)$ and $S^2_{box}(x_c)$. We recall that this is not yet the sought avalanche shape and fluctuations. Rather, it is the expectation of the size $S(x)$ inside a box of size 1, given that the avalanche does not touch any of the two boundaries $x = \pm 1/2$. We will have to vary the boundary points in order to extract the shape $\langle S(x) \rangle$ of avalanches which vanish at the boundary points, but not before. This is the objective of the next section.

For later reference, we note that
\[
\int_{-1/2}^{1/2} dx \frac{x_c}{x_c} S^1_{box}(x) = - \frac{3 f'(x) + f(x) F(x) - 2 F_0 [x f(x) + F(x)]}{6 \delta_S} \bigg|_{-1/2}^{1/2} = \frac{2 F_0^2}{3 \delta_S} = \frac{256 \pi^8}{9 \Gamma(1/2)^8} = 0.00534401, \tag{66}
\]
\[
\int_{-1/2}^{1/2} dx \frac{x_c}{x_c} S^2_{box}(x) = 2.3030 \times 10^{-6}. \tag{67}
\]

IV. FROM $S_{box}(x)$ TO THE SHAPE $S(x)$: SCALING ARGUMENTS, ETC

A. Probability of finding an avalanche of extension $\ell$ and probability for seed position

The probability to have an avalanche of size $\ell$ is, according to Eqs. (23) and (26) to leading order in $w$, given by
\[
P_\ell(x) = -w \int_{x_1}^{x_2} dx \frac{\partial^2 \tilde{u}(x)}{\partial r_1 \partial r_2}
\]
\[
= w \frac{1}{\ell^3} \int_{-1/2}^{1/2} dx \frac{(4x^2 - 1) f''(x) + 24 [x f'(x) + f(x)]}{4}
\]
\[
+ \cdots \approx 4 F_0 \frac{w}{\ell^2} + \cdots \equiv 8 \pi \sqrt{3 \frac{w}{\ell^3}} + \cdots, \tag{68}
\]
with $F_0$ defined in Eq. (62).

It is interesting to note that the integrand in Eq. (68) gives the probability to have the seed at position $x$. More precisely, the probability that the seed was at position $x$ inside an avalanche extending from $-1/2$ to $1/2$ is
\[
P_{\ell=1}(x) = \frac{(4x^2 - 1) f''(x) + 24 [x f'(x) + f(x)]}{32 \pi \sqrt{3}}. \tag{69}
\]

This function starts with a cubic power at the boundary. We give a series expansion below in Eq. (89).

B. Basic scaling relations and consequences

In general, the size of an avalanche scales as $S(\ell) \sim \ell^{d+\xi}$. For the BFM, the latter reduces to
\[
S(\ell) \sim \ell^4. \tag{70}
\]
The proportionality constant is calculated in Eq. (81) below.

Let us now solve the instanton equation (35) with the source (36) for arbitrary $r_1$ and $r_2$. This can be achieved by observing that, as a function of $|r_2 - r_1|$, we have
\[
\tilde{u}(x) \sim \tilde{u}(x) \sim \frac{1}{|r_2 - r_1|} \equiv \eta \delta(x - x_c) \equiv \frac{\eta}{|r_2 - r_1|} \left( \frac{x - x_c}{|r_2 - r_1|} \right). \tag{71}
\]

Thus $\eta \sim |r_2 - r_1|^{-1}$ and
\[
\tilde{u}_1^{r_1, r_2}(x) = |r_2 - r_1| \frac{\tilde{u}(x - r_1 + (r_2 - 1)/2)/r_2 - r_1}{r_2 - r_1} \left( \frac{x - r_1}{r_2 - r_1} \right), \tag{72}
\]
\[ S_{\text{box}}^{\ell}(x_c) = \int_{r_1}^{r_2} dx \, \partial_{\ell_1, r_1}(x) \]
\[ = |r_2 - r_1|^2 \frac{S_{\text{box}}^{\ell_1 - 1}(x_c - (r_1 + r_2)/2)}{r_2 - r_1}. \]  
(73)

This yields the shape of an avalanche of extension \( \ell \) is consistent with the dimension of an avalanche \( S \) per length \( \ell \), i.e. \( S/\ell \sim \ell^d \).

Now, the (unnormalized) shape of an avalanche of extension \( \ell \) is according to Eq. (46) obtained as
\[ S_{\ell=r_2-r_1}(x) = -\partial_x \partial_{\ell_1} S_{\text{box}}^{\ell_1-1}(x). \]  
(74)

Using Eq. (72), this yields
\[ S_{\ell=1}(x) = -\partial_x \partial_{\ell_1} \left[ |r_2 - r_1|^2 S_{\text{box}}^{\ell_1}(x - (r_1 + r_2)/2) \right]_{r_1=-\ell/2}^{r_1=\ell/2} = [2 - 2x\partial_x + (x^2 - \frac{1}{3})\partial_{\ell_1}^2] S_{\text{box}}^{\ell_1}(x). \]  
(75)

We note that this function grows cubically at the boundary, consistent with our scaling argument (6). To achieve this, the factor of \( |r_2 - r_1|^2 \) in Eq. (75) is crucial: Were the exponent larger than 2, then the growth would be linear. Were it smaller, the function (75) would become negative.

Integrating by parts, we obtain, using Eq. (66),
\[ \int_{-1/2}^{1/2} dx \, S_{\ell=1}(x) = 6 \int_{-1/2}^{1/2} dx \, \partial_{\ell_1} S_{\text{box}}^{\ell_1}(x_c) = \frac{4F_{0\ell}^2}{\xi_1}. \]  
(76)

Similarly, we find for the order-\( \eta^2 \) term
\[ S_{\ell=1}^{\eta^2}(x) = -\partial_x \partial_{\ell_1} \left[ |r_2 - r_1|^2 S_{\text{box}}^{\ell_1}(x - (r_1 + r_2)/2) \right]_{r_1=-\ell/2}^{r_1=\ell/2} = [20 - 8x\partial_x + (x^2 - \frac{1}{3})\partial_{\ell_1}^2] S_{\text{box}}^{\ell_1}(x). \]  
(77)

This implies
\[ \int_{-1/2}^{1/2} dx \, S_{\ell=1}(x) = 30 \int_{-1/2}^{1/2} dx \, \partial_{\ell_1} S_{\text{box}}^{\ell_1}(x_c). \]  
(78)

Note that, according to Eqs. (45)–(47), \( S_0(x) \) and \( S_2(x) \) are not yet properly normalized to give the expectation of the shape of an avalanche. For this purpose, let us define, with the help of Eq. (68),
\[ \langle S(x) \rangle_\ell := \frac{wS_0(x)}{P_{\text{aval}}(\ell)} = \frac{S_{\ell=1}(x/\ell)}{4F_0^2}, \]  
(79)

\[ \langle S^2(x) \rangle_\ell := \frac{wS_2(x)}{P_{\text{aval}}(\ell)} = \frac{S_{\ell=1}(x/\ell)}{4F_0^2}. \]  
(80)

These functions give the shape of an avalanche given that the avalanche extends from \(-\frac{1}{2}\) to \(\frac{1}{2}\), as well as its fluctuations, including the amplitude. For the total size \( \langle S \rangle_\ell = \int_{-\ell/2}^{\ell/2} dx \langle S(x) \rangle_\ell \) and the integral of the second moment \( \langle S^2(x) \rangle_\ell \) we find
\[ \int_{-\ell/2}^{\ell/2} dx \, \langle S(x) \rangle_\ell = \frac{F_0^2}{\xi_1} \ell^4 = 0.000 \, 736 \, 576 \, \ell^4, \]  
(81)

\[ \int_{-\ell/2}^{\ell/2} dx \, \langle S^2(x) \rangle_\ell = 5.290 \, 44 \times 10^{-8} \ell^7. \]  
(82)

C. Results for the shape and its second moment

We give explicit formulas for \( \langle S(x) \rangle_\ell \) and \( \langle S^2(x) \rangle_\ell \) below. They are plotted in Fig. 3. We did not succeed in finding much simpler expressions. While in particular the expression for the second moment \( \langle S^2(x) \rangle_\ell \) is lengthy, its ratio with the squared first moment is almost constant, given by
\[ \frac{\langle S^2(x) \rangle_\ell}{\langle S(x) \rangle_\ell^2} \approx 1.635 \pm 0.02. \]  
(83)

This can be seen in Fig. 3. The explicit formulas are
While these expressions are cumbersome, one can work with a converging Taylor series. An expansion in \((\frac{1}{2} - x)(\frac{1}{2} + x)\) respecting the Taylor expansion at the boundary is

\[
\langle S(x) \rangle_{\ell=1} = \frac{1}{21} \left( \frac{1}{4} - x^2 \right)^3 + \frac{3}{28} \left( \frac{1}{4} - x^2 \right)^4 + \frac{2}{7} \left( \frac{1}{4} - x^2 \right)^5 + \frac{5}{6} \left( \frac{1}{4} - x^2 \right)^6 + \left( \frac{18}{7} - \frac{\xi_1}{1540 F_0} \right) \left( \frac{1}{4} - x^2 \right)^7
\]

\[
+ \left( \frac{1}{4} - x^2 \right)^8 \left( \frac{33}{4} - \frac{7 \xi_1}{1760 F_0} \right) + \frac{1}{4} \left( \frac{1}{4} - x^2 \right)^9 \left( -\frac{\xi_1}{55 F_0} + \frac{5 \xi_1}{34398} + \frac{572}{21} \right)
\]

\[
+ \frac{1}{4} - x^2 \right)^{10} \left( \frac{3 \xi_1 + 78.078}{2548} - \frac{3 \xi_1}{40 F_0} \right) + \cdots, \tag{86}
\]

\[
\langle S(x)^2 \rangle_{\ell=1} = \frac{1}{273} \left( \frac{1}{4} - x^2 \right)^6 + \frac{5}{294} \left( \frac{1}{4} - x^2 \right)^7 + \frac{503}{7644} \left( \frac{1}{4} - x^2 \right)^8 + \frac{309}{1274} \left( \frac{1}{4} - x^2 \right)^9
\]

\[
+ \frac{561}{637} - \frac{529 \xi_1}{3898440 F_0} \right) \left( \frac{1}{4} - x^2 \right)^{10} + \frac{937}{294} - \frac{8641 \xi_1}{7796880 F_0} \left( \frac{1}{4} - x^2 \right)^{11}
\]

\[
+ \left( -\frac{531}{85765680 F_0} + \frac{\xi_1}{25137} + \frac{485}{42} \right) \left( \frac{1}{4} - x^2 \right)^{12} + \cdots, \tag{87}
\]

\[
\langle S(x)^2 \rangle_{\ell=1} \langle S(x) \rangle_{\ell=1} = \frac{21}{13} + \frac{3}{13} \left( \frac{1}{4} - x^2 \right)^2 + \frac{87}{208} \left( \frac{1}{4} - x^2 \right)^3 + \frac{411}{416} \left( \frac{1}{4} - x^2 \right)^4 \left( \frac{8877}{3328} - \frac{307 \xi_1}{19448 F_0} \right)
\]

\[
+ \frac{1623}{208} - \frac{127 \xi_1}{2992 F_0} \right) \left( \frac{1}{4} - x^2 \right)^5 + \left( -\frac{31591 \xi_1}{311168 F_0} + \frac{74 \xi_1}{9633} + \frac{1281987}{53248} \right) \left( \frac{1}{4} - x^2 \right)^6
\]

\[
+ \left( -\frac{732863 \xi_1}{1311680 F_0} + \frac{5543 \xi_1}{134862} + \frac{8216901}{106496} \right) \left( \frac{1}{4} - x^2 \right)^7 + \cdots. \tag{88}
\]

For completeness, we also give a series expansion for \(P_{\ell=1}(x)\),

\[
P_{\ell=1}(x) = \frac{\xi_1}{8 \sqrt{3} \pi} \left[ \frac{2}{7} \left( \frac{1}{4} - x^2 \right)^3 + \frac{5}{14} \left( \frac{1}{4} - x^2 \right)^4 + \frac{4}{7} \left( \frac{1}{4} - x^2 \right)^5 + \frac{1}{4} \left( \frac{1}{4} - x^2 \right)^6 + \frac{12}{7} \left( \frac{1}{4} - x^2 \right)^7 + \frac{33}{14} \left( \frac{1}{4} - x^2 \right)^8
\]

\[
+ \frac{5 \xi_1}{22932} \left( \frac{1}{4} - x^2 \right)^9 + \frac{11(\xi_1 - 12.168)}{6552} \left( \frac{1}{4} - x^2 \right)^{10} + \frac{205 \xi_1 - 2.895984}{22932} \left( \frac{1}{4} - x^2 \right)^{11} + \cdots. \tag{89}
\]
FIG. 4. Twenty avalanches with extension $\ell = 200$, rescaled to $\ell = 1$. Here $n = 2871$ is the number of samples used for the average.

V. NUMERICAL VALIDATION

We verified our findings with large-scale numerical simulations. To this aim, we consider the equation of motion discretized in space, started with a kick of size 1,

$$\partial_t \dot{u}_i(t) = \dot{u}_{i+1}(t) + \dot{u}_{i-1}(t) - 2\dot{u}_i(t) + \sqrt{\dot{u}_i(t)} \xi(t), \quad (90)$$

$$\langle \xi(t) \xi(t') \rangle = \delta(t - t'), \quad (91)$$

$$\dot{u}_0(0) = \delta_i, \quad (92)$$

Since we work in the Brownian force model, these equations do not depend on the shape of the interface before the avalanche and one can always start from a flat interface. This would not be the case for finite-range disorder. For the same reason, we can choose to put the seed at zero and to not change the seed position between avalanches.

One further has to discretize in time, using a step size $\delta t$. A naive implementation would lead to a factor of $\sqrt{\delta t}$ in front of the noise term. Thus the limit of $\delta t \to 0$ is difficult to take. Here we use an algorithm proposed in [37] and further developed for the problem at hand in [36]. The idea is to use the conditional probability $P(\dot{u}_i(t + \delta t) | \dot{u}_i(t), \dot{u}_{i\pm 1}(t))$, where $\dot{u}_{i\pm 1}(t)$ are assumed to remain fixed. From this probability, which is a Bessel function, $\dot{u}_i(t + \delta t)$ is then drawn. Sampling of the Bessel function is achieved by its clever decomposition into a sum of Poisson times $\Gamma$ functions, for which efficient algorithms are available. This algorithm scales linearly with the time discretization $\delta t$. It is explained in detail in Ref. [36], Appendix H.

We run our simulations for a system of size 410 and time step $\delta t = 0.01$, producing a total of 526,929,535 avalanches. Since $P(\ell) \sim 1/\ell^3$, most avalanches have a small extension and the statistics for them will be good. On the other hand, small avalanches have important finite-size corrections and thus are not in the scaling limit. In the following, we will show all our data, reminding the reader of these two respective shortcomings.

Let us start by showing 20 avalanches of extension 200 (see Fig. 4). One sees that there are substantial fluctuations in the shape, roughly consistent with the theoretically expected domain plotted in Fig. 3.

Let us next study the shape of the discretized avalanches close to the boundary. To this aim we plot in Fig. 5 the mean shape of all avalanches with a given size, taken to the power $1/3$. One can see that, for a given point $i$ from the boundary, these curves converge against a limit when increasing $\ell$. This confirms our boundary-shape conjecture made in the Introduction. In addition, we see that the shape taken to the power $1/3$ converges against a straight line with slope $\sqrt{1/2}$, as predicted [see Eqs. (8) and (86)]. However, there is a nonvanishing boundary-layer length $\ell_B$ such that

$$\langle S(x - r_1) \rangle \simeq \frac{1}{3}(x - r_1 - \ell_B)^3 + \cdots. \quad (93)$$

Our extrapolations in Fig. 5 show that

$$\ell_B \approx 2. \quad (94)$$
In order to faster converge to the field-theoretic limit, we define the total extension $\ell$ of an avalanche to be

$$\ell := \ell_{\text{discretized}} - 2\ell_B,$$

where $\ell_{\text{discretized}}$ is the number of points which advanced in an avalanche. This definition can be interpreted such that the avalanche extends to the middle between the first nonmoving point and the first moving one. As such, it contains some arbitrariness. The choice is motivated as follows: A good test object is the total size $\langle S \rangle$ of an avalanche of extension $\ell$, which we know from Eq. (81) to be

$$\langle S \rangle = 0.000 736 576 \ell^4.$$

Figure 6 confirms this; it also shows that the approach to this limit has finite-size corrections, which we estimate as

$$\langle S \rangle \simeq 0.000 736 576 \ell^4 \left[ 1 + \frac{30}{\ell^2} + O(\ell^{-3}) \right].$$

We now come to a check of the shape itself. To this aim, we plot in Fig. 8 the mean shape of our avalanches, rescaled to $\ell = 1$. We see that these curves converge rather nicely to the predicted universal shape (84), even for relatively small sizes. We then turn to the fluctuations. In Fig. 9 we plot the ratio $\langle S^2(x) \rangle / \langle S(x) \rangle^2$. A glance at the right-hand side of Fig. 3 shows that it is almost constant, equal to $1.635 \pm 0.02$. Our simulations even allow us to see the variation of this ratio. Finally, we plot on the left-hand side of Fig. 10 the difference between the numerically obtained shape $\langle S(x) \rangle$ and its theoretically predicted value. On the right-hand side we make the same comparison for the ratio $(S^2(x))/\langle S(x) \rangle^2$. The precision achieved is a solid confirmation of our theory.

VI. CONCLUSION

In this article, we considered the spatial shape of avalanches at depinning. We gave scaling arguments showing that close to the boundary in $d = 1$, the average shape grows as a power law with the roughness exponent $\zeta$. We then obtained analytically the full shape functions $\langle S(x) \rangle$ for the BFM, where each degree of freedom sees a force which behaves as a random walk.

It would be interesting to extend these considerations in several directions. First of all, one could ask what the shape function would be in higher dimensions. The techniques developed here will not immediately carry over: The domain where the advance of the avalanche is nonzero should be compact, but may have a fractal boundary. So we could still...
calculate the shape inside a given domain, but it would be meaningless to prescribe the boundary as in \(d = 1\), where there are only two boundary points.

Second, one can ask how the shape changes for short-range correlated disorder, by including perturbative corrections. Work in this direction is left to future investigations.

Finally, it would be interesting to obtain the avalanche shape for long-range elasticity, which is relevant for fracture, contact-line wetting, and earthquakes. The complication here is that an avalanche may contain several connected components.

### ACKNOWLEDGMENTS

We are grateful to Mathieu Delorme for providing the Python code which generated the avalanches used in the numerical verification.

#### APPENDIX A: SOLUTION OF \( \tilde{u}''(x) + \tilde{u}(x) = -\lambda \delta(x) \) WITH \( \lambda \to -\infty \)

Let us give a solution for the instanton equation with a single source \([36]\), i.e.,

\[
\tilde{u}''(x) + \tilde{u}(x) = -\lambda \delta(x). \tag{A1}
\]

The ansatz

\[
\tilde{u}_{st}(x) := -\frac{6}{(|x| + x_0)^2} \tag{A2}
\]

satisfies Eq. (A1) with

\[
-\lambda = \frac{24}{x_0^3}. \tag{A3}
\]

Note that this is an exact solution for a single source, but it also gives the leading behavior in the case of several sources, in particular how the nontrivial instanton solution with two sources at \(x = \pm 1/2\) can be regularized around its singularities.

#### APPENDIX B: FINITE-ENERGY INSTANTON SOLUTIONS

We want to solve the instanton equation

\[
\tilde{u}''(x) + \tilde{u}(x)^2 = 0. \tag{B1}
\]

Multiplying with \(\tilde{u}'(x)\) and integrating once gives

\[
\frac{\tilde{u}'(x)^2}{2} + \frac{\tilde{u}(x)^3}{3} = \mathcal{E}. \tag{B2}
\]

Solving for \(\tilde{u}'(x)\) yields

\[
\tilde{u}'(x) = \pm \sqrt{2\mathcal{E} - \frac{2}{3}\tilde{u}(x)^3}, \tag{B3}
\]

\[
\tilde{u}(x) = \sqrt{\frac{2\mathcal{E} - \frac{2}{3}\tilde{u}(x)^3}{\sqrt{2\mathcal{E} - \frac{2}{3}\tilde{u}(x)^3}}} = \pm 1. \tag{B4}
\]

Integrating once, we find

\[
\frac{\tilde{u}_2F_1\left(\frac{1}{2}, \frac{1}{2}; 1; \frac{-\tilde{u}(x)^3}{\sqrt{2\mathcal{E}}}\right)}{\sqrt{2\mathcal{E}}} = \pm x + \text{const.} \tag{B5}
\]

These solutions are real for \(\mathcal{E} > 0\), which we consider first (see Fig. 11):

\[
x_0 := \lim_{u \to -\infty} \frac{\tilde{u}_2F_1\left(\frac{1}{2}, \frac{1}{2}; 1; \frac{-\tilde{u}(x)^3}{\sqrt{2\mathcal{E}}}\right)}{\sqrt{2\mathcal{E}}} = -\frac{\sqrt{3}\Gamma\left(\frac{1}{2}\right)\Gamma\left(\frac{3}{4}\right)}{\sqrt{2\pi\sqrt{2}}} \tag{B6}
\]

The solution stops at the last argument of the hypergeometric function being 1, i.e., \(u = \sqrt{3\mathcal{E}}\), such that

\[
x_0 := \frac{\tilde{u}_2F_1\left(\frac{1}{2}, \frac{1}{2}; 1; \frac{-\tilde{u}(x)^3}{\sqrt{2\mathcal{E}}}\right)}{\sqrt{2\mathcal{E}}} \bigg|_{u \to \sqrt{3\mathcal{E}}} = \frac{\sqrt{3}\sqrt{2}\Gamma\left(\frac{3}{4}\right)}{\sqrt{\pi\sqrt{2}}}. \tag{B7}
\]

Note that \(x_c = -2x_0\). This allows us to write a solution symmetric around \(x = 0\) (with the right-hand side being
FIG. 11. Solutions \( x(\tilde{u}) \), patching the two branches together at \( x = 0 \), as well as its derivatives. The solid curve is the solution for \( E = E_1 > 0 \), the dashed the solution for \( \tilde{E} = -E_1 < 0 \). positive),

\[
\pm x = \frac{\sqrt[3]{3\sqrt{2\pi E}}^{\frac{1}{2}}}{\sqrt[6]{3\sqrt{2\pi E}}^{\frac{1}{2}}} - \tilde{u} F_1\left(\frac{1}{3}, \frac{1}{2}, \frac{7}{6}; \frac{1}{2}; \tilde{u}^2\right). \tag{B8}
\]

The instanton has extension 1 for

\[
E_1 := \left(\frac{\sqrt[3]{3\sqrt{2\pi E}}^{\frac{1}{2}}}{\Gamma\left(\frac{3}{5}\right)}\right)^6 = \frac{52488\pi^3 \Gamma\left(\frac{1}{4}\right)^6}{\Gamma\left(\frac{5}{6}\right)^6}. \tag{B9}
\]

This yields, for the positive branch of the solution with extension 1,

\[
\pm x = \frac{1}{6} - \frac{\tilde{u} F_1\left(\frac{1}{3}, \frac{1}{2}, \frac{7}{6}; \frac{1}{2}; \tilde{u}^2\right)}{\sqrt{2E}}. \tag{B10}
\]

Now we consider solutions for \( \tilde{E} := -E > 0 \). Using Pfaffian transformations for the hypergeometric function yields

\[
\pm x = \frac{\sqrt{6\tilde{u}} F_1\left(\frac{1}{2}, 1; \frac{7}{3}; \frac{3\tilde{E}}{2\pi} + \frac{3\tilde{E}}{2\pi} + \tilde{u}^2\right)}{\sqrt{-3\tilde{E} - \tilde{u}^2}} + \frac{\sqrt{3\sqrt{2\pi E}}^{\frac{1}{2}}}{\sqrt{\tilde{E}} \Gamma\left(\frac{1}{2}\right)}. \tag{B11}
\]

Note that this solution is real; the shift brings the solution around \( x = 0 \). It has extension 1 in the \( x \) direction for

\[
\tilde{E}_1 := \left(\frac{\sqrt{3\sqrt{2\pi E}}^{\frac{1}{2}}}{\Gamma\left(\frac{3}{5}\right)}\right)^6 = \frac{8\pi^3 \Gamma\left(\frac{1}{4}\right)^6}{3 \Gamma\left(\frac{5}{6}\right)^6}. \tag{B12}
\]

There

\[
\pm x = \frac{\sqrt{6\tilde{u}} F_1\left(\frac{1}{2}, 1; \frac{7}{3}; \frac{3\tilde{E}}{2\pi} + \tilde{u}^2\right)}{\sqrt{-3\tilde{E} - \tilde{u}^2}} + \frac{1}{2} \bigg|_{\tilde{E} = \tilde{E}_1}. \tag{B13}
\]

As is easily checked numerically, it agrees with the solution (52) of [36]

\[
\tilde{u}(x) = -6P\left(x + 1/2; g_2 = 0, g_3 = \frac{\Gamma\left(\frac{1}{4}\right)^{18}}{(2\pi)^6}\right). \tag{B14}
\]

The function \( P \) is the Weierstrass \( P \) function. By construction, the solution \( f(x) \equiv \tilde{u}(x) \) satisfies the following relations, which we give together for convenience:

\[
f^2(x) + f''(x) = 0, \tag{B15}
\]

FIG. 12. Shown on the left is the data reverse engineered from [33], slightly shifted in the \( x \) direction and rescaled in the \( y \) direction to collapse with our result for \( S(x) \), normalized to 1. The exponents from top to bottom are \( a = 1/4, 1/3, \) and \( 1/2 \). Contrary to the claims of [33], \( a = 1/4 \) is not the best fit, but \( a = 1/3 \) is, corresponding to a cubic behavior at the boundary. On the right is the consistency with our theory (top curve). This is compared to the theory in [33] and its numerical validation: The lower dashed curve is the theory for avalanches with a large aspect ratio \( S/\ell^2 \), while the dots are the numerical verification from the same reference.
\begin{equation}
\frac{3}{2} f^3(x) + f'(x)^2 = -36g_3 \equiv -2\tilde{c}_1, \tag{B16}
\end{equation}

\begin{equation}
\frac{9}{2} f(x) f''(x) - f'(x)^2 = 36g_3 = 2\tilde{c}_1. \tag{B17}
\end{equation}

Using these relations, some terms which in general are not total derivatives can be written as such, e.g.,

\begin{equation}
f'(x)^2 = \frac{d^2}{dx^2} \left[ \frac{1}{5} f(x)^2 - \frac{3}{5} \overline{\sigma}_1 x^2 \right]. \tag{B18}
\end{equation}

**APPENDIX C: REANALYSIS OF THE DATA OF REF. [33]**

In Ref. [33] it was claimed that when averaging over all avalanches of a given extension $\ell$, close to the boundary the scaling function grows as $\langle S(x) \rangle_\ell \sim (x - \ell/2)^4$. This was supported by a log-log plot of the data (see Fig. 14 of Ref. [33]). This procedure is dangerous, due to the boundary layer studied in Sec. IV C, which shifts the effective size of an avalanche. It is more robust to take $S(x)$ to the inverse expected power and verify whether the resulting plot yields a straight line close to the boundary of the avalanche. This is done in Fig. 12. One can clearly see in the left plot that the data are most consistent with $a = \frac{1}{4}$, equivalent to a cubic growth close to the boundaries. We also show on the right-hand side of Fig. 12 that these data are consistent with our theory; note that the amplitude has been adjusted, since it could not be extracted from [33].


