

Analysis of the Stop-and-Restart procedure for solving random 3-SAT

A large deviation study of the
Generalized Unit Clause search heuristic.

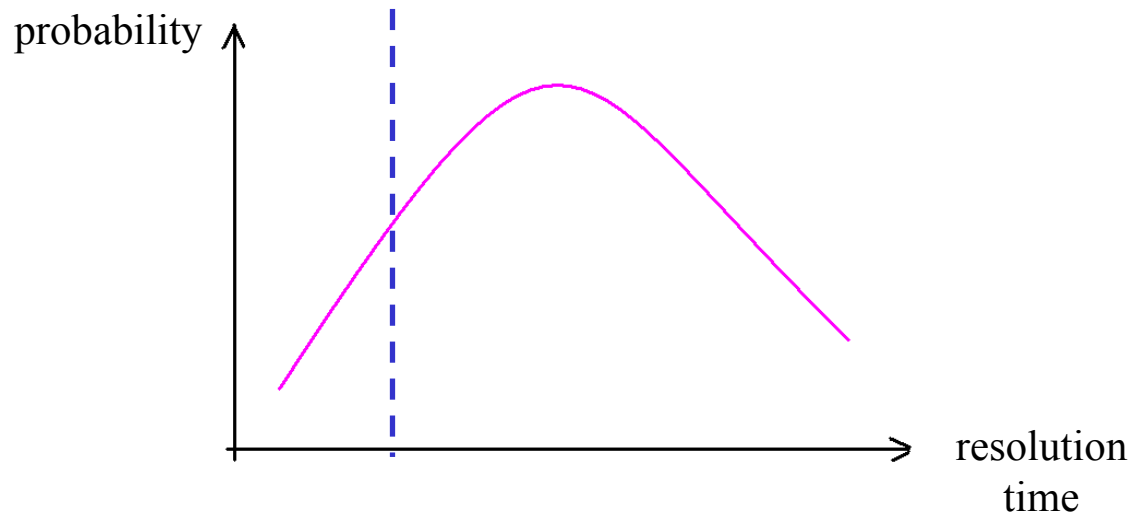
Simona Cocco *University Louis Pasteur, Strasbourg*

Rémi Monasson *Ecole Normale Supérieure, Paris*

<http://www.lpt.ens.fr/~monasson>

Introduction

Branch-and-bound algorithm fl **non deterministic heuristic**



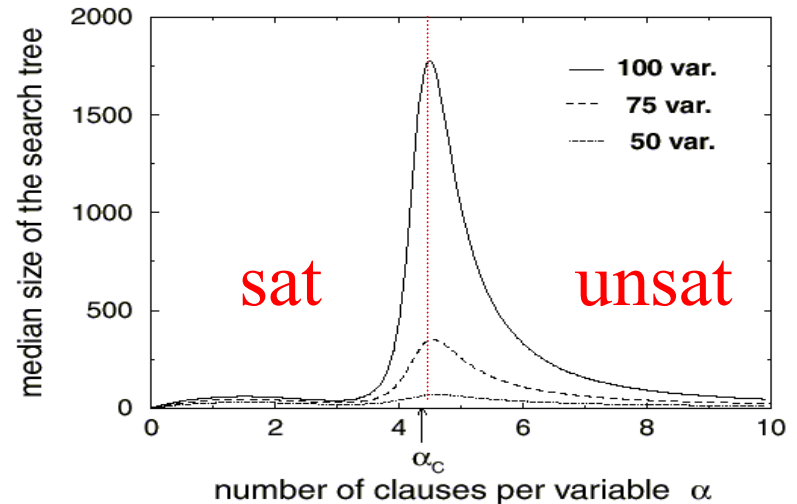
Idea: exploit the (left) tail of the distribution of resolution times

Stop & Restart ! (incomplete ...)

Dubois et al. '93,
Gomes et al. '00

Random 3-SAT

$$\alpha = \frac{\text{nb. of clauses}}{\text{nb. of variables}} \rightarrow \alpha_C \approx 4.3$$



Davis-Putnam-Loveland-Logeman algorithm = heuristic + backtracking

Generalized unit-clause (GUC): pick literal in shortest clause

Mitchell, Selman, Levesque '92; Crawford, Auton '93; Gent, Walsh '94;
Chao, Franco '86, '90; Chvatal, Szmeredi '88; Achlioptas '01

Resolution trajectories

clauses with 3 var.

α

“dynamics”
of

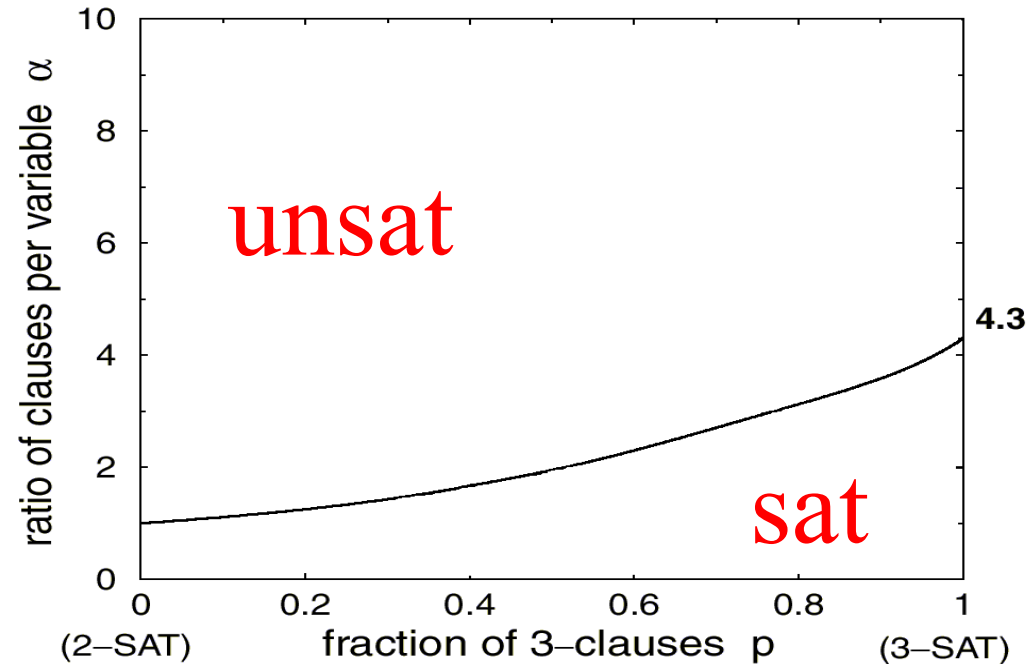


the
algorithm

clauses with 2 or 3 var.

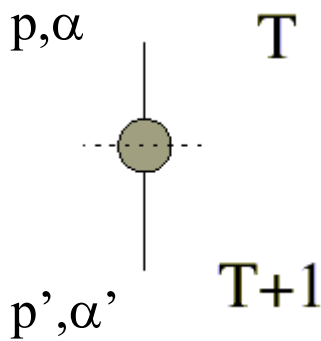
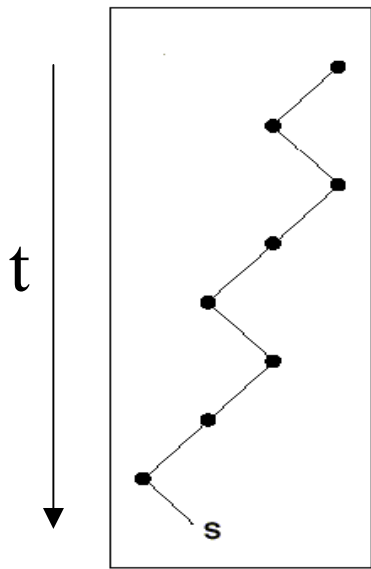
α, p

*phase diagram of the
2+p-SAT model*



Monasson, Zecchina, Kirpatrick, Selman, Troyansky '99
Achlioptas, Kirovsi, Kranakis, Krizanc '01

Satisfiable and easy instances $\alpha < 3.003$



$$p(0) = 1, \alpha(0) = \alpha_0$$

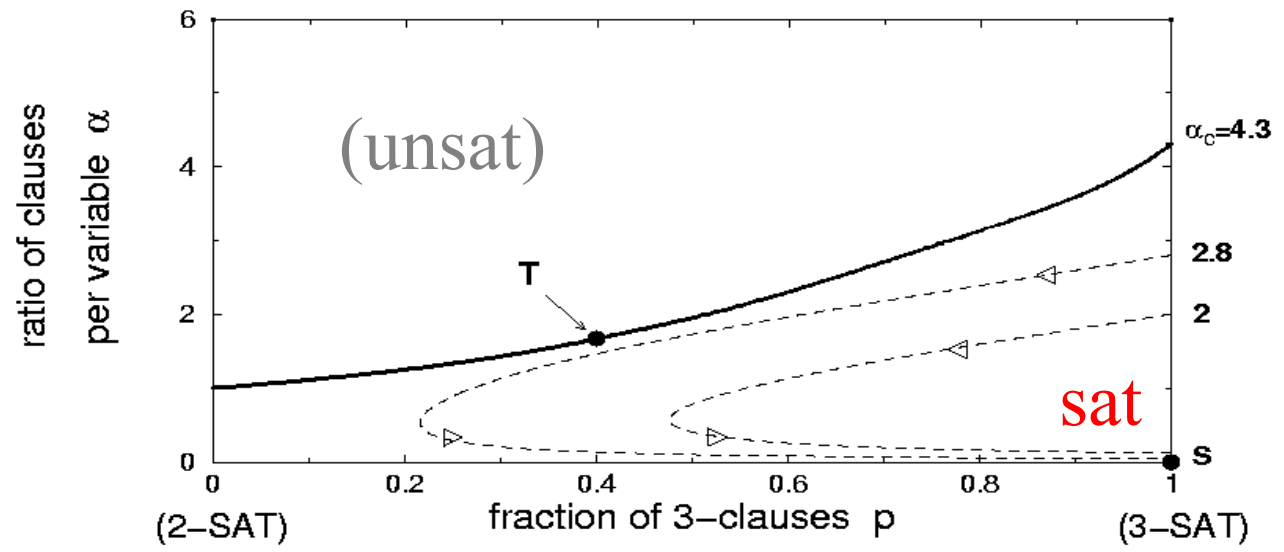
$$\frac{dp}{dt} = F_p(p, \alpha, t)$$

$$\frac{d\alpha}{dt} = F_\alpha(p, \alpha, t)$$

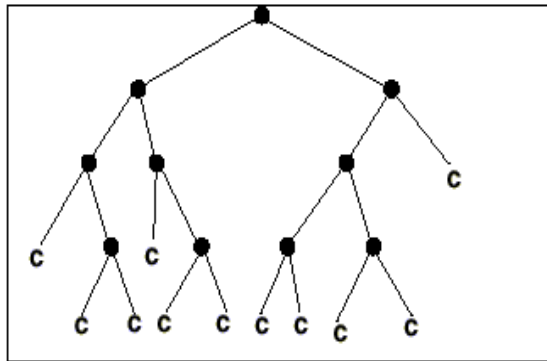
(ODE)

Chao,
Franco '90

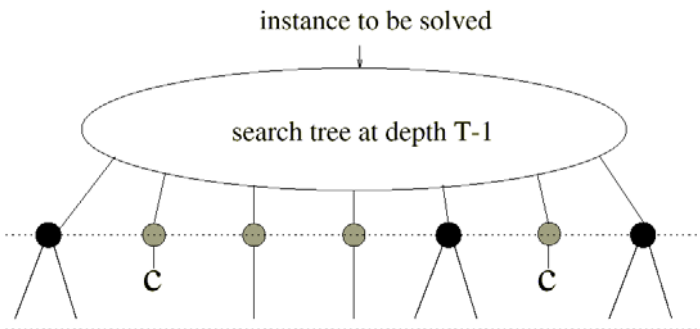
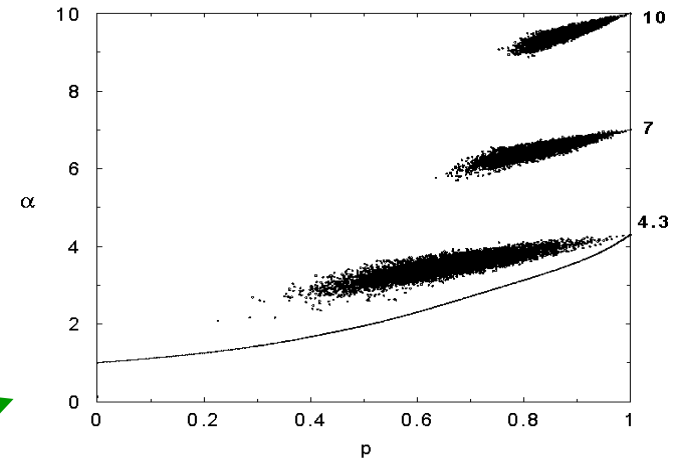
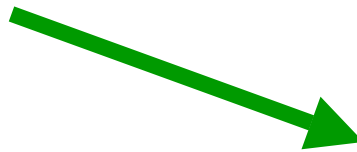
Frieze,
Suen '96



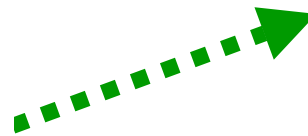
Unsatisfiable, hard instances $\alpha > 4.3$



DPLL induces a non Markovian evolution of the search tree



depth
0
T
T+1



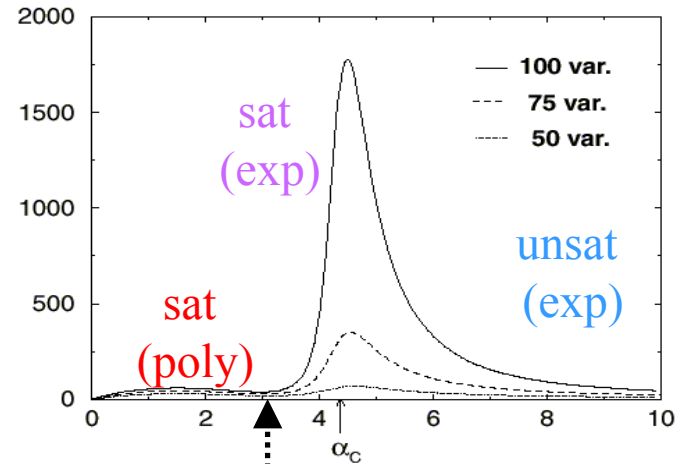
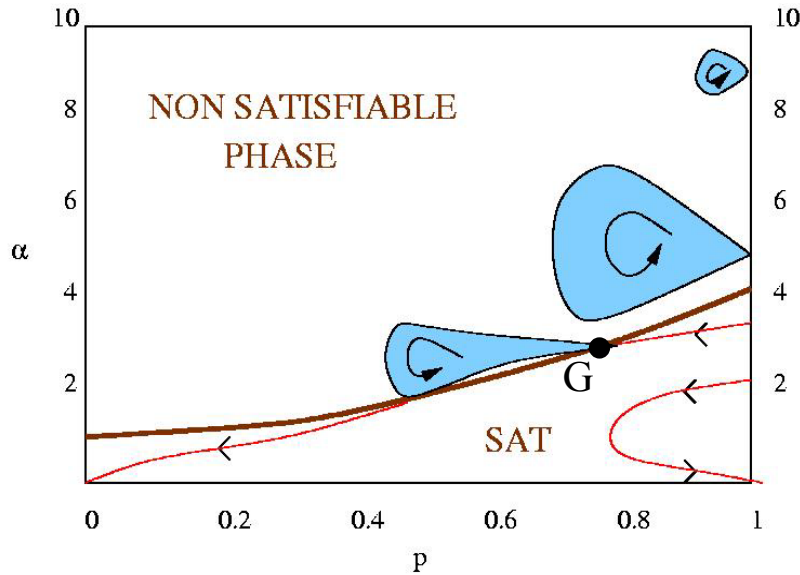
Imaginary, and parallel building up of the search tree

one branch: $p(t), \alpha(t)$
ODE

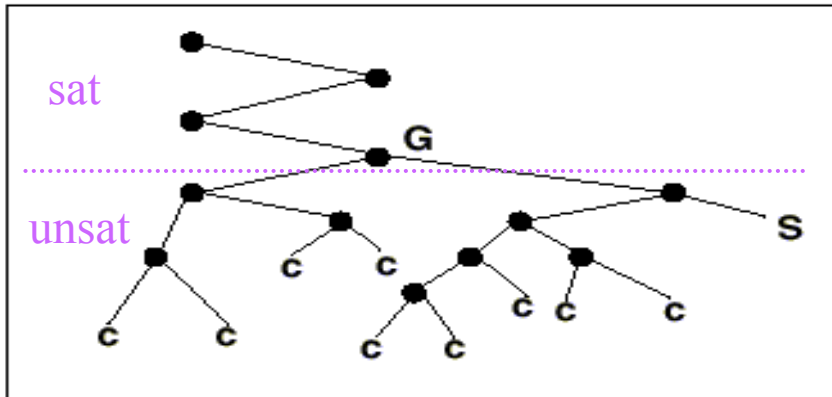


many branches: $b(p, \alpha, t)$
PDE

The polynomial/exponential crossover

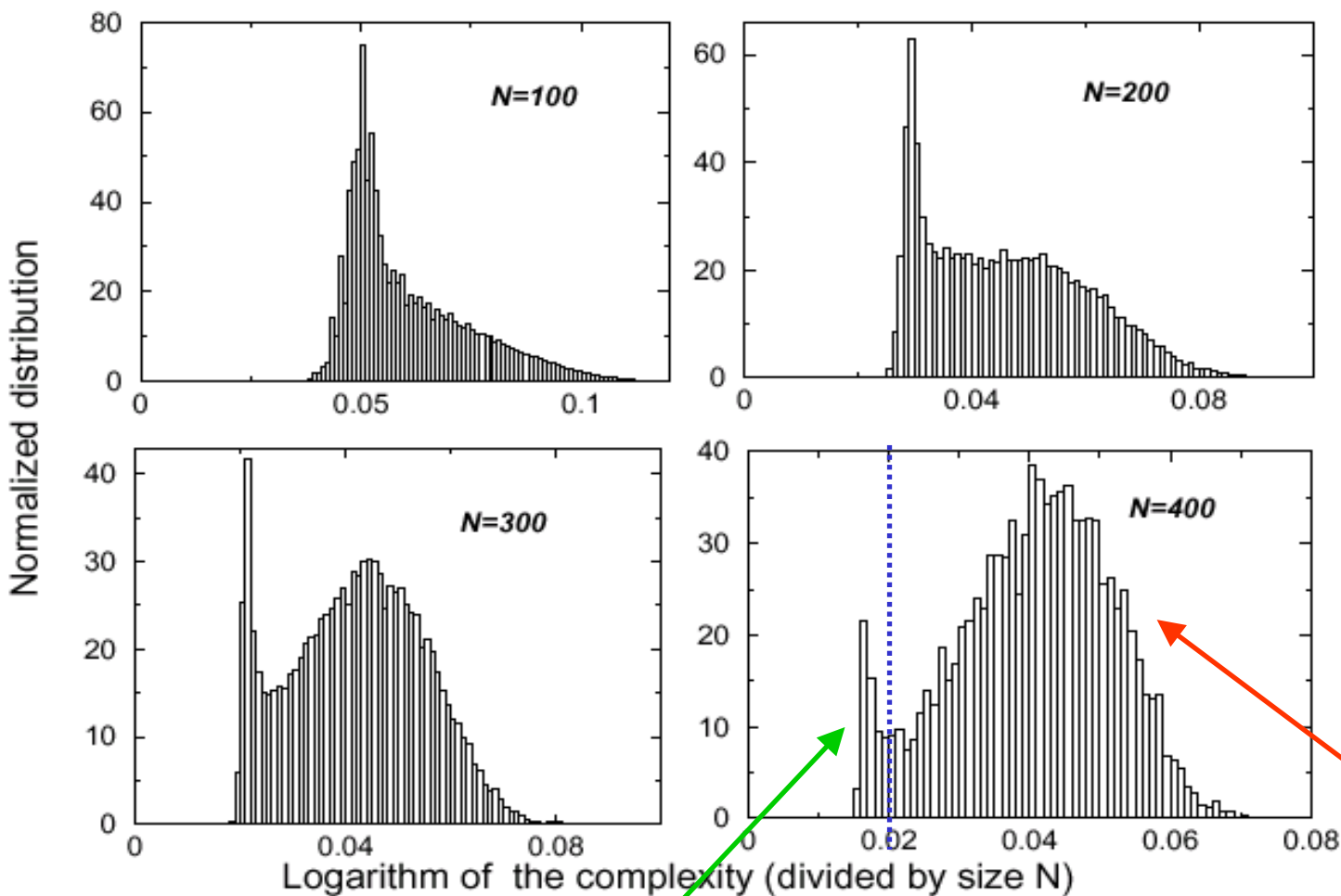


“dynamical” transition
(depends on the heuristic)



Satisfiable, hard instances $3.003 < \alpha < 4.3$

Fluctuations of complexity for finite instance size



Histograms of solving times

$$\alpha=3.5$$

Exponential regime
Complexity
 $= 2^{0.035 N}$

Linear regime

Very rare! frequency $= 2^{-0.011 N}$

Application to Stop & Restart resolution

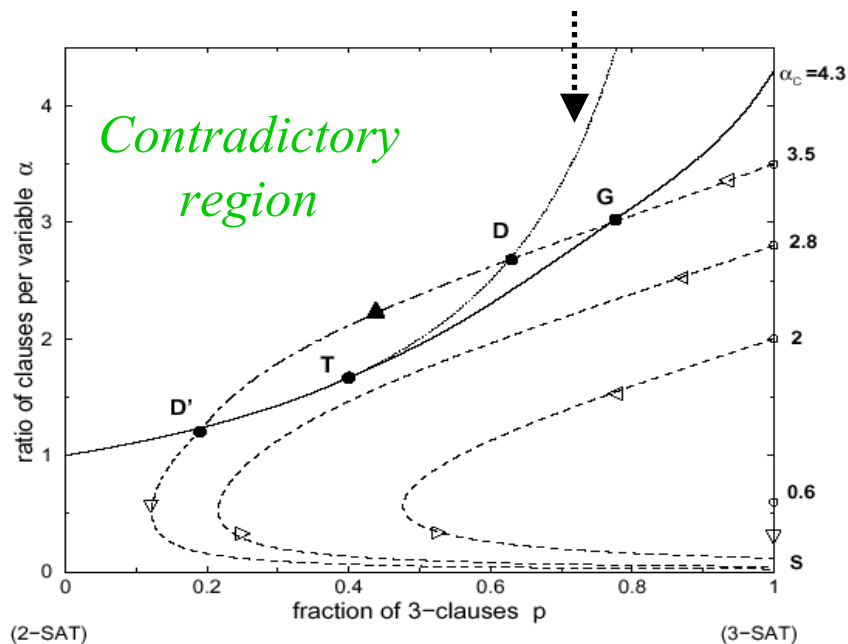
Resolution through systematic stop-and-restart of the search:

- stop algorithm after time N ;
- restart until a solution is found.

Cocco, R.M. '02

Time of resolution : $2^{0.035 N}$ $\dots\dots\dots$ $2^{0.011 N}$

Halt line for first branch = accumulation of unitary clauses



Easy resolution trajectories manage to survive in the contradictory region!

Analysis of the probability of survival (*I*)

Probability of survival
of the first branch with
clause populations
 C_1, C_2, C_3

$$B(C_1, C_2, C_3; T + 1) = \sum_{C'_1, C'_2, C'_3=0}^{\infty} K(C_1, C_2, C_3, C'_1, C'_2, C'_3; T) B(C'_1, C'_2, C'_3; T)$$

Transition matrix

$$K(C_1, C_2, C_3; C'_1, C'_2, C'_3; T) = \binom{C'_3}{C'_3 - C_3} \left(\frac{3}{N-T}\right)^{C'_3 - C_3} \left(1 - \frac{3}{N-T}\right)^{C_3} \sum_{w_2=0}^{C'_3 - C_3} \left(\frac{1}{2}\right)^{C'_3 - C_3} \binom{C'_3 - C_3}{w_2} \\ \times \left\{ (1 - \delta_{C'_1}) \sum_{z_2=0}^{C'_2} \binom{C'_2}{z_2} \left(\frac{2}{N-T}\right)^{z_2} \left(1 - \frac{2}{N-T}\right)^{C'_2 - z_2} \sum_{w_1=0}^{z_2} \left(\frac{1}{2}\right)^{z_2} \binom{z_2}{w_1} \delta_{C_2 - C'_2 - w_2 + z_2} \delta_{C_1 - C'_1 - w_1 + 1} + \delta_{C'_1} \right. \\ \left. \times \sum_{z_2=0}^{C'_2 - 1} \binom{C'_2 - 1}{z_2} \left(\frac{2}{N-T}\right)^{z_2} \left(1 - \frac{2}{N-T}\right)^{C'_2 - 1 - z_2} \sum_{w_1=0}^{z_2} \left(\frac{1}{2}\right)^{z_2} \binom{z_2}{w_1} \delta_{C_2 - C'_2 - w_2 + z_2 + 1} [\delta_{C_1 - w_1} (1 - C_1/2/(N-T))^{C_1 - 1}] \right\},$$

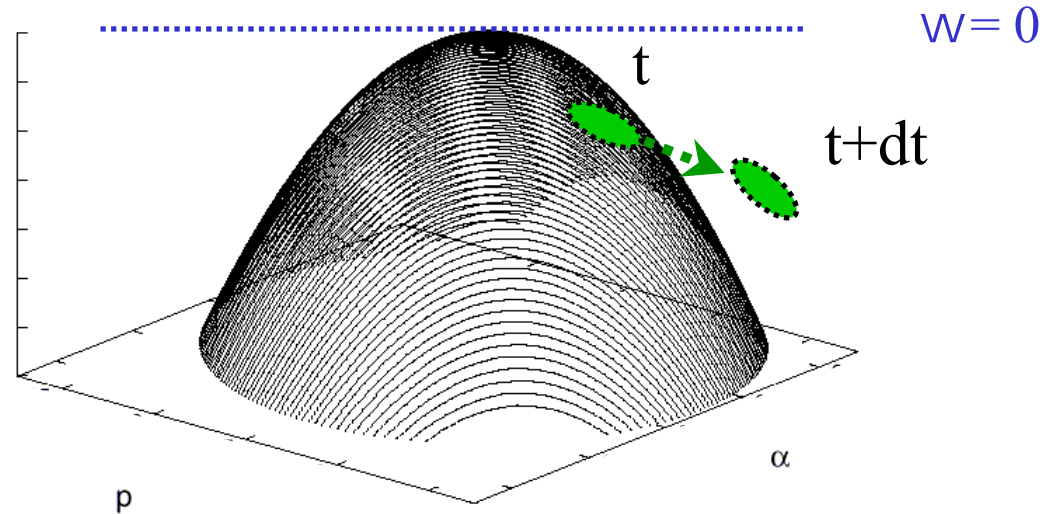
- $B(C_1, C_2, C_3; T) \sim \exp[-N \mathcal{W}(c_1, c_2, c_3; t)]$ where $c_i = C_i/N$, $t = T/N$
- two cases: $C_1 = O(1)$ (safe regime), $C_1 = O(N)$ (dangerous regime).

Analysis of the probability of survival (II)

- *Safe regime:*

$$c_1 = 0$$

$$w = \log(\text{probability})/N$$

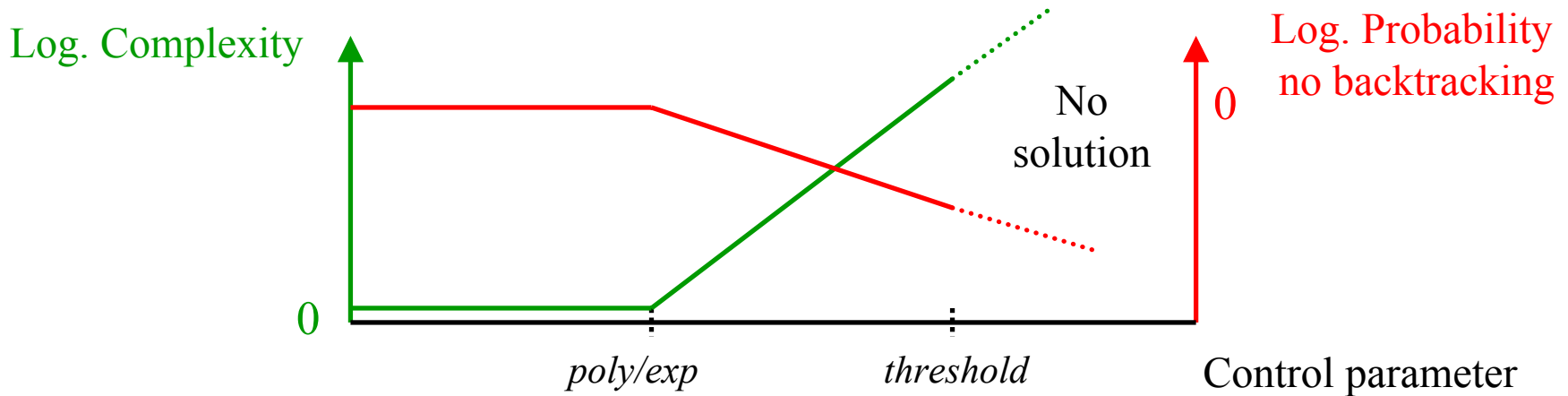


$$\frac{\partial \omega}{\partial t} = \mathcal{H} \left[p, \alpha, \frac{\partial \omega}{\partial p}, \frac{\partial \omega}{\partial \alpha}, t \right] \quad (\text{PDE})$$

- *Dangerous regime:* $c_1 = O(1)$, $w < 0$

Conclusions

- Statistical physics concepts and techniques can be useful to reach a non rigorous but quantitative understanding of algorithms
(*phase diagram, dynamical trajectories, growth processes,*)
- Stop-&-Restart procedure: when do we stop?
from the present study: cut-off time = size of the instance



- Further developments:
analysis of trees generated by more complex heuristics,